

2025

Presented by LBStech



LBS Tech

Location Based Service

CONTENTS.

I.
**Market Trend &
Problem**

II.
Solution

III.
Utilization

IV.
Scalability

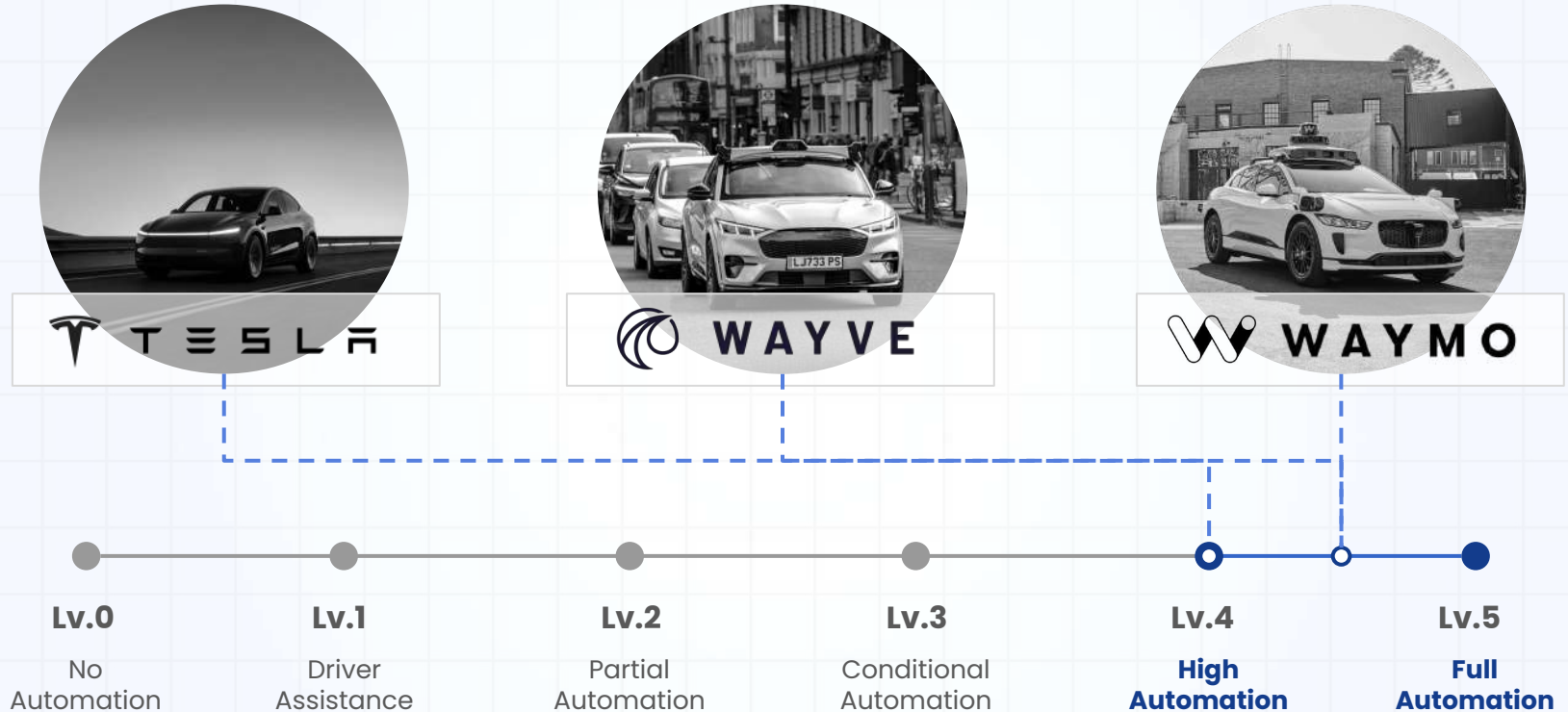


I.

Market Trend & Problem

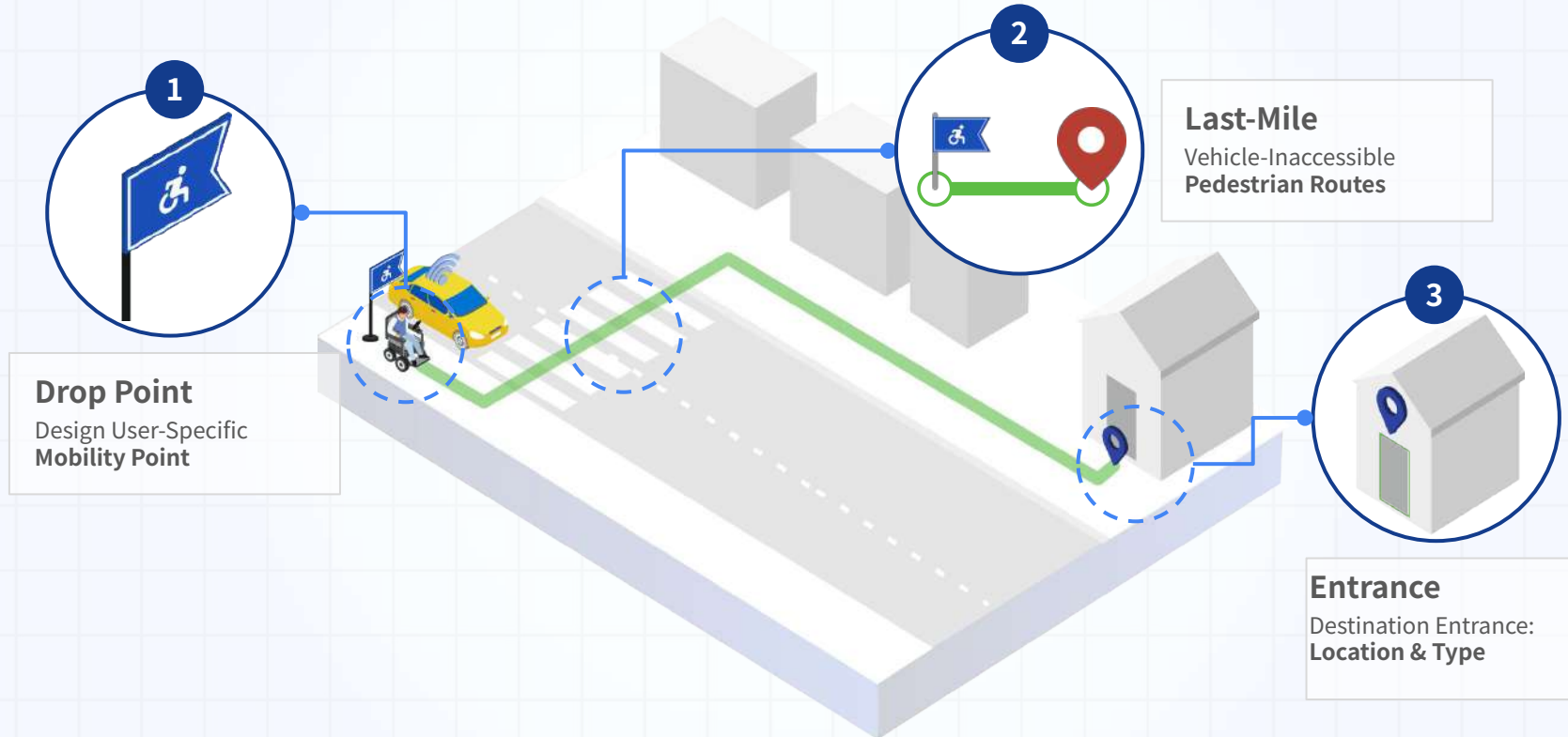
01. Mobility Market

Advancement of Autonomous Driving Technology



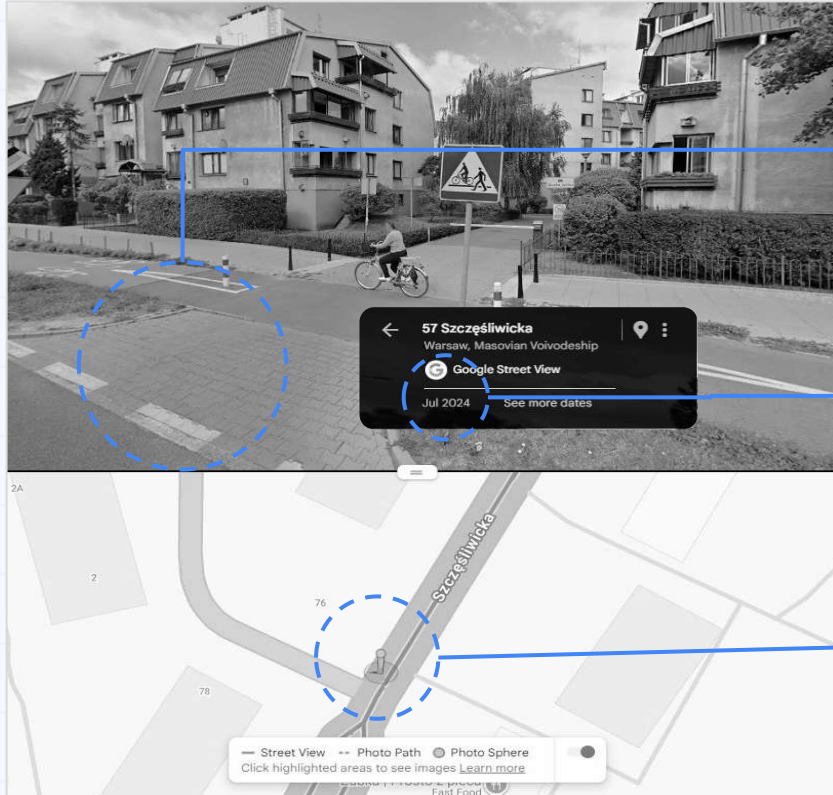
02. Necessity of Last-Mile

A Walk Journey to the Destination, “Last-Mile”



03. Problem

Challenges in Walkway Data Collection System



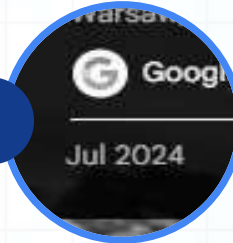
1



Vehicle-Based Data Collection

Necessity of
pedestrian-based data collection

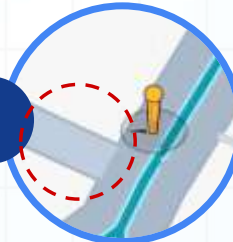
2



Outdated Data

Necessity of
continuous update of collected data

3



Areas with Missing Data

Necessity of
automated data collection & monitoring

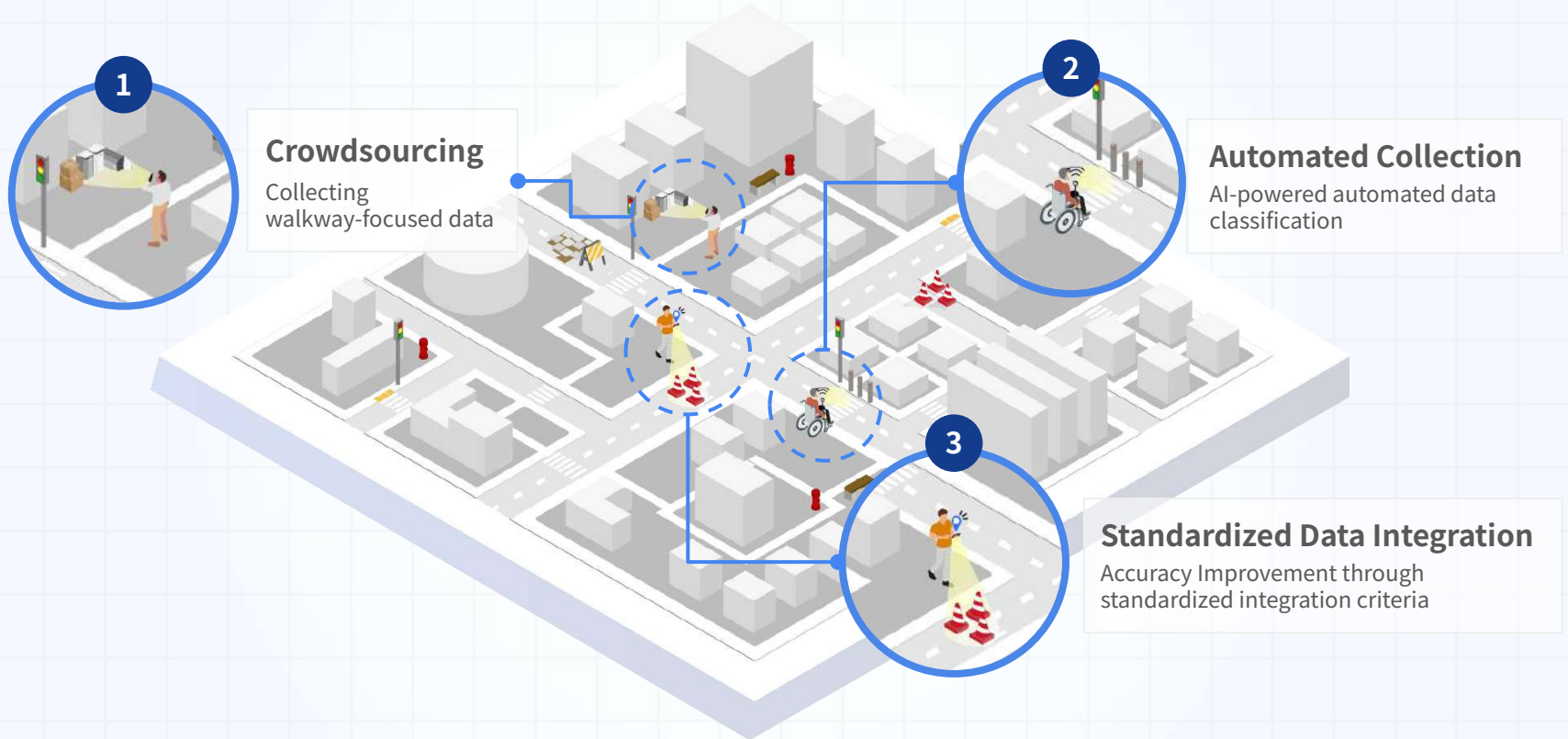


II.

Solution

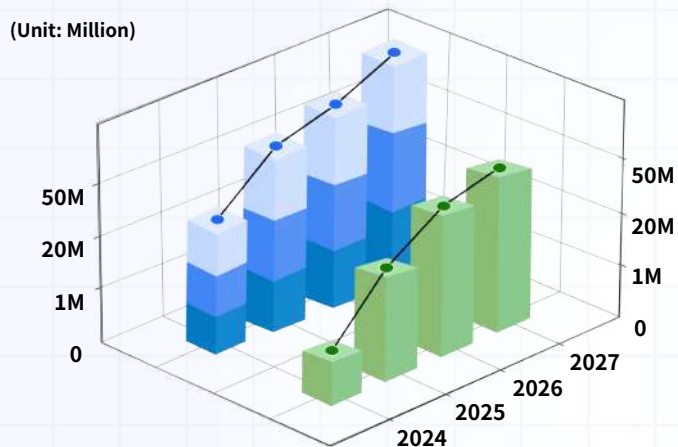
01. Solution

Automated Solution from Data Collection to Integration



02. Crowdsourcing-Based Data Collection

Ongoing Data Collection by Citizen Participation



| | 2024 | 2025 | 2026 (Prediction) | 2027 (Prediction) |
|----------------------|----------|-----------|----------------------|----------------------|
| ESG (Corporate) | 100 | 300 | 500 | 1,000 |
| CSR (Public org.) | 500 | 1,000 | 1,500 | 2,000 |
| Public Project | 1,000ppl | 4,050ppl | 20,000ppl | 90,000ppl |
| Volunteer | | 13,746ppl | 50,000ppl | 100,000ppl |

Obstacle walkway Accessibility Oversea

2025 New Collectors

3,050 ppl

Data Collection

7,840,806 pcs



Door

1,557,451



Entrance

1,795,035



Walkway

1,079,178

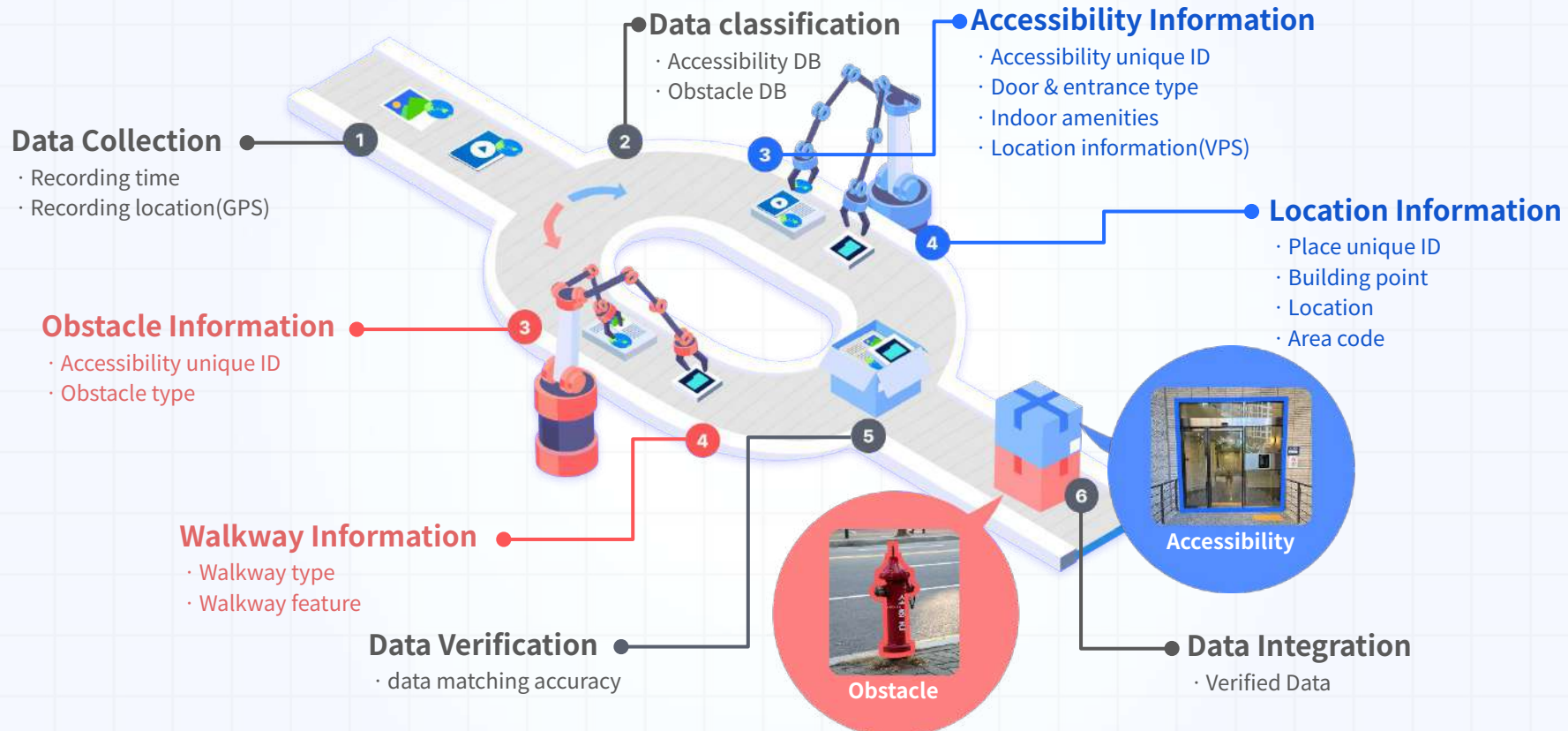


Amenity

766,668

03. Automated Data Collection & Classification System

AI-Powered Automated Data Collection & Classification



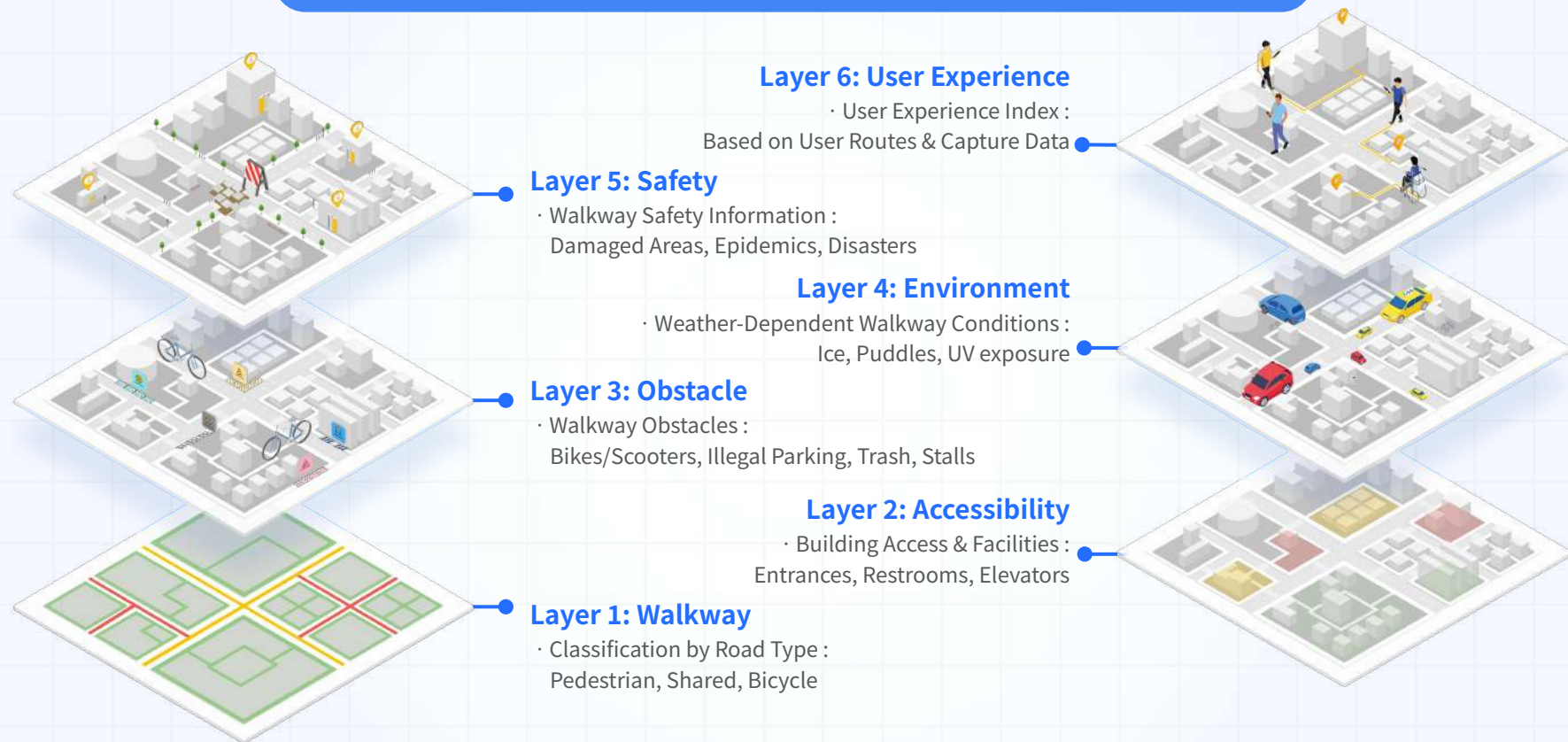
03. Automated Data Collection & Classification System

AI-Powered Automated Data Collection & Classification



04. DB Standardization

Applying Updated Accurate Data by DB Standardization





III.

Utilization

01. Solution Utilization

Universal Last-Mile Solution for ALL Mobility Types

API/SDK

Walkway/accessibility data → API/SDK for external parties

1

Delivery Robot

User-type algorithm-based routing for delivery robots

2

Autonomous Driving

Autonomous driving integration through walkway monitoring and control

3

Mobile, IoT Service

User-specific route guidance through connected traffic IoT



02. Navigation for Mobility-Challenged Users

User-Centric IoT & Wearable Navigation



IoT-linked walkway navigation
for Visually Impaired

AR-Pedestrian Tour Service
for Wheelchair Users



「Smart Watch Integration Demo
for Visually Impaired」



「Crosswalk Signal Integration Demo
for Visually Impaired」



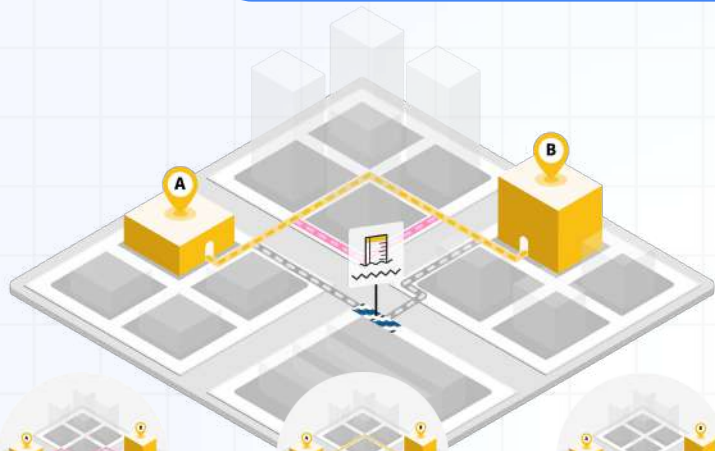
「Walkway Tour Demo
for Wheelchair Users」



「Walkway Navigation Demo
for Wheelchair Users」

03. Route Algorithm Integration

Delivery Robot Navigation via Walkway Route Algorithms



Visually Impaired

Wheelchair User

Senior & People

Detect Formula

$$F(x) = \frac{f(x+h)-f(x)}{h}$$

$$(x-x_1)^2 + (y-y_1)^2 + (z-z_1)^2 = (t_{r1}-b-s_1) c$$

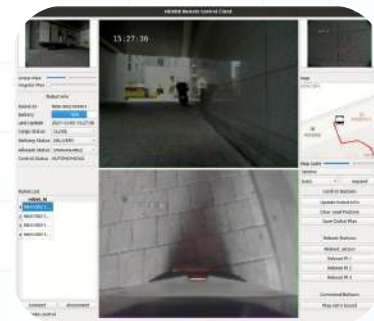
$$(x-x_3)^2 + (y-y_3)^2 + (z-z_3)^2 = (t_{r3}-b-s_3) c$$



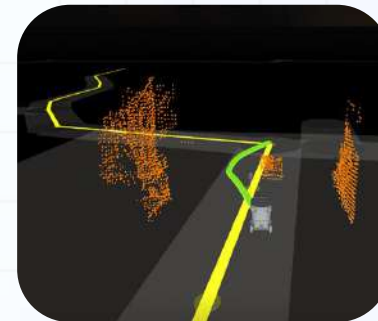
「Konkuk Univ. Campus Demo」



「Yeonsei Univ. Campus Demo」



「Robot monitoring system」



「Object-Aware Routing Sample」

04. Last-Mile Connection

Autonomous-Linked Last-Mile PoC Project



First/Last-Mile Model
with Autonomous Shuttle

Autonomous Delivery Robot
Route Optimization

Robot Taxi Integration by
User-Specific Drop Points



「2026 Ohmio Collaboration discussion」



「Autonomous Shuttle Pilot Project」



IV.

Scalability

01. Global Expansion

LBS Tech Global Collaborations



London, Barking and Dagenham **Pilot Project**

Implementing wheelchair-accessible navigation services with local authorities



New York, Barrier-free Campus Project

Practicum project for the barrier-free campus in collaboration with Univ. of Rochester

Dubai, Navigation Pilot through Local Network

MOU Signed with Ascendant Digital at the 2023 AAE.
Pilot of pedestrian pathway data-based navigation services



Vietnam, Ho Chi Minh Cith Pilot Project

Launching AI navigation for the visually impaired in key districts, partnering with local organizations

Spain Barcelona Pilot Project

Pilot Project in the Barcelona Area
Collaboration with ONCE, the Spanish National Organization for the Blind

01. Global Expansion - Vietnam

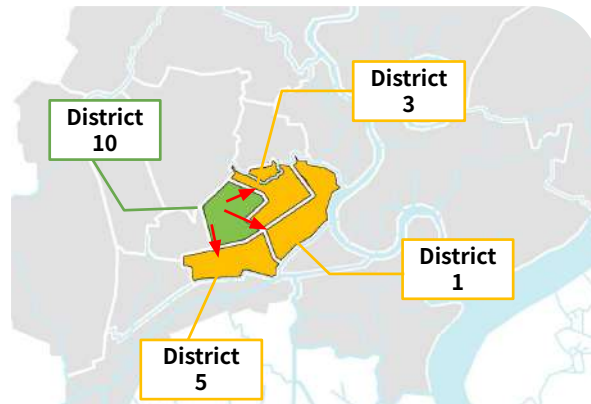
Mobility & Access Service PoC for Barrier-Free Smart City

Smart City Project in Vietnam



- Data collection of walkway & building accessibility
- Store infrastructure improvement & certification
- Demo of walkway navigation for visually impaired
- Demo of contactless order/payment system for visually impaired

Achievements



- **23% increase** in sales at stores through demo project
- **16% expansion** in average travel range for testers
- Business coverage expanded from Dist. **10** to **1, 3, 5**
- Local network with **MSD, DRD, ISCM**

01. Global Expansion - US

Barrier-Free Campus with University-Industry partnership

Practicum with Univ. of Rochester

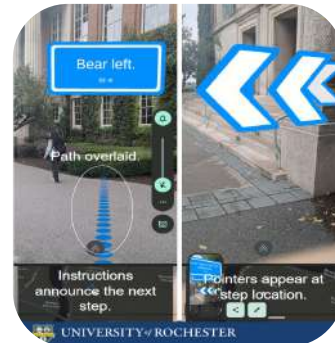


- Technical support for data collection
- AR-campus service with student participation
- API support for user-specific route algorithms
- University-based collaborative networks

Achievements



< Rochester Univ. Data Sample >



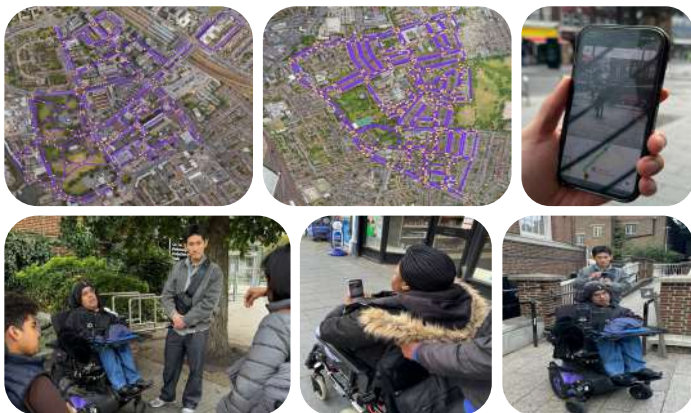
< AR Service Development >

- Case study of **XR-based accessibility enhancement**
- Study on improving service usability through **AR- glasses integration**
- Verification of tech support process via **API**
- Expansion of campus project in **Cornell, Carnegie**

01. Global Expansion - UK

Barrier-Free Town Project with Last-Mile Service

London Smart-Town Project



- Walkway data collection in Barking, Dagenham
- PoC of walkway navigation service for “Vision Zero”
- Last-mile based walkway mobility & tourism information service
- PoC Project with local wheelchair users

Achievements



< WMCA LOI signed >



West Midlands
Combined Authority



- Project expansion to **Birmingham, West Midlands**
- **LOI Signed** for collaboration with local authorities
- Implement last-mile services integrated with **autonomous driving**
- Validation of last-mile **barrier-free town** project

02. Service Scalability

Function Expansion through Integration

Kiosk



Wearable Devices



Autonomous Wheelchair



| Version | v2.0 | v3.0 | v3.5 | v4.0 |
|------------|--------------------------|-----------------------------|----------------------------------|--|
| Function | Kiosk Connection | Wearable Devices Connection | Autonomous Wheelchair Connection | Autonomous driving Connection |
| User | Mobility-Challenged user | + IoT, Machine | + Seniors | + Vehicle |
| Technology | Optimized Interface | Walkway Providing System | Standardized Spatial Data | Integration of Autonomous Driving Technology |
| Year | ~2025 | | ~2027 | |
| | | | ~2029 | |

03. Collaboration

Data Collaboration via API, SDK

PED HUB

- Human verification & AI-based auto validation
- Pedestrian road / Accessibility / Location DB
- Data classified into 7 layers :User experience, Safety incidents, environment, obstacles & facilities, Buildings & roads
- Periodical update : Event of incident / 3 months / 1 years

Collection

- Using Door Scanner/Road Scanner
- Video Collection(Sensor)

LBS Tech
Collaboration
Architecture

Application

- Data : API/SDK
- Application : PED-Map, G-EYE
- IoT : AR glasses, Watch
- Mobility : Delivery, AI Camera



04. Technological Expertise

Proven Technological Expertise through Global Awards



< President's Volunteer Service Award >

Global Awards



<2026 CES>

BOI of Travel & Tourism



< 2025 CES Innovation Awards >
Honoree of Human Security 4 All



< 2023 MWC GLOMO Awards >
Best Mobile Use for Inclusive

Patents & Award





*Every Move, Every Step, For
Everyone*